

CONTROL I

ELEN3016

The Root Locus Method

(Lecture 12)

Overview

- First Things First!
- Introductory Examples
- Construction Rules
- Tutorial Exercises & Homework
- Next Attraction!

First Things First!

- Temporary arrangement – online access
http://dept.eie.wits.ac.za/~vanwyk/ELEN3016_2012/
- Deadline for Labs
 - Lab assessment interviews need to start on 19 October'15.

Complex Numbers – Revision

- Algebra of Complex Numbers

- Modulus-argument form: $z = |z|e^{j\angle z} \equiv |z| \angle z$

- Product of complex numbers:

$$\begin{aligned}(s-p) \times (s-z) &= \left(|s-p|e^{j\angle(s-p)}\right) \times \left(|s-z|e^{j\angle(s-z)}\right) \\&= |s-p||s-z|e^{j\angle(s-p)}e^{j\angle(s-z)} \\&= |s-p||s-z|e^{j[\angle(s-p)+\angle(s-z)]}\end{aligned}$$

Complex Numbers – Revision

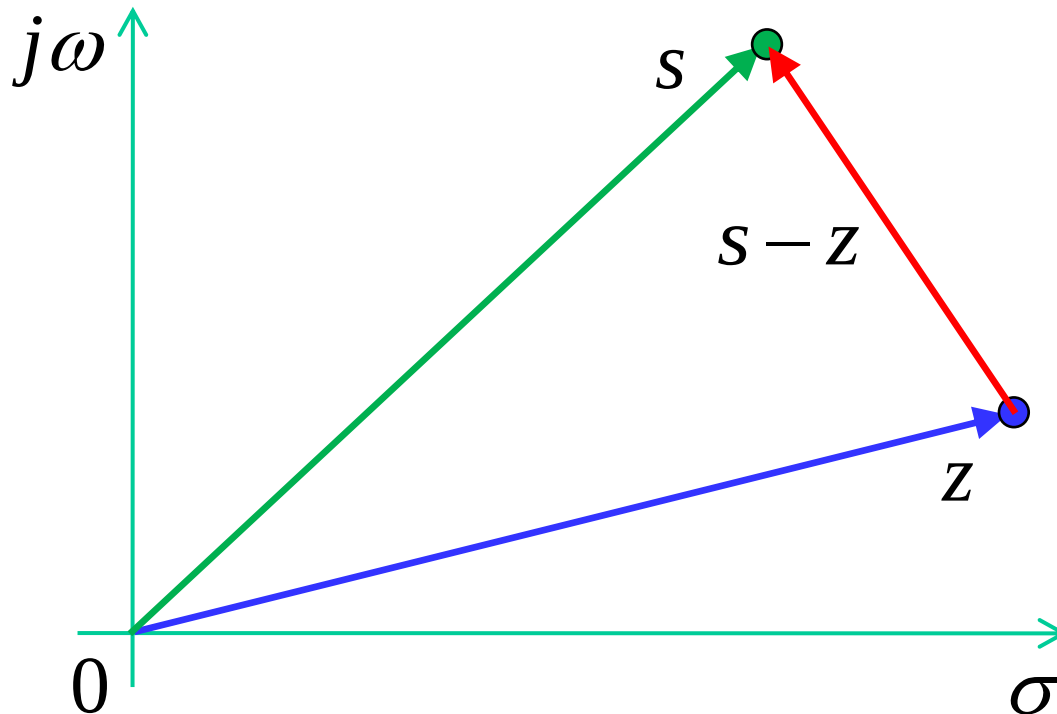
- Algebra of Complex Numbers (cont'd)

- Quotient of complex numbers:

$$\begin{aligned}\frac{s-p}{s-z} &= \frac{|s-p|e^{j\angle(s-p)}}{|s-z|e^{j\angle(s-z)}} \\ &= \frac{|s-p|}{|s-z|} \times \frac{e^{j\angle(s-p)}}{e^{j\angle(s-z)}} \\ &= \frac{|s-p|}{|s-z|} e^{j[\angle(s-p)-\angle(s-z)]}\end{aligned}$$

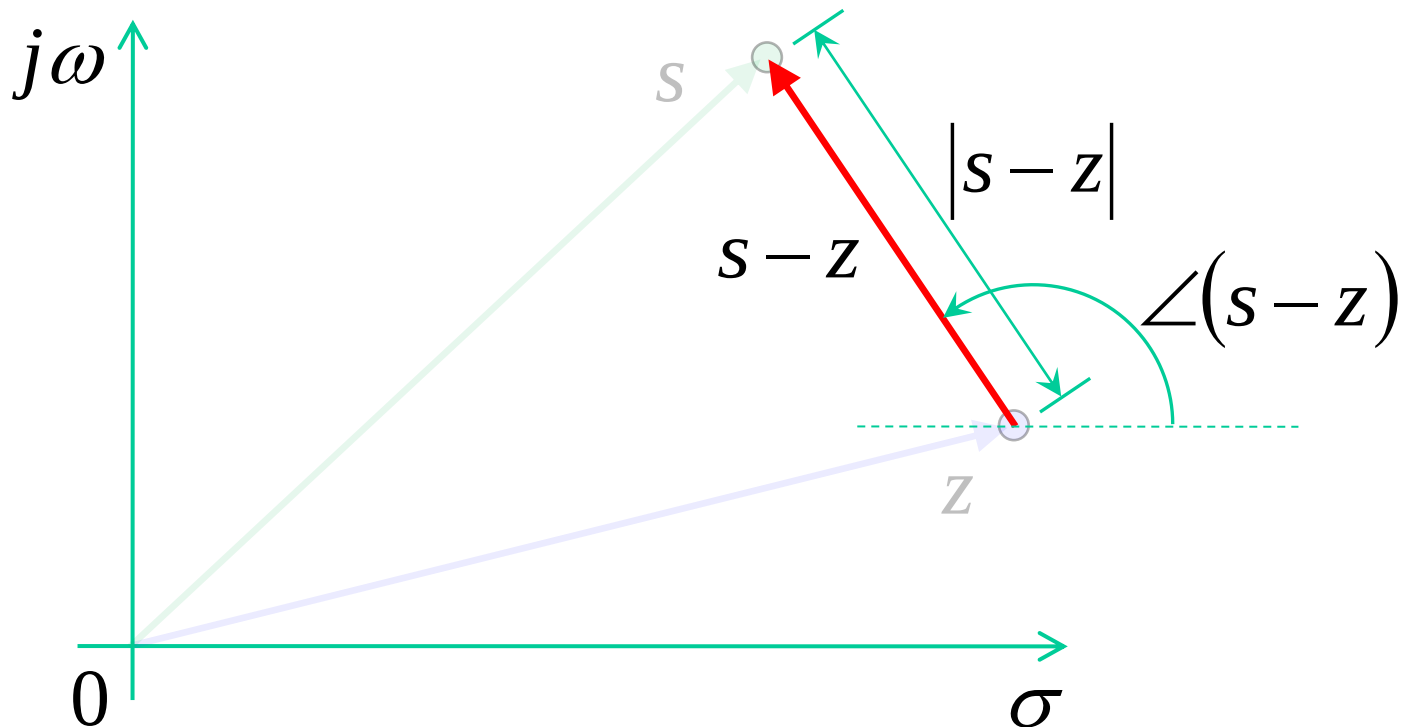
Complex Numbers – Revision

- Algebra of Complex Numbers (cont'd)
 - Visualisation of $(s - z)$:



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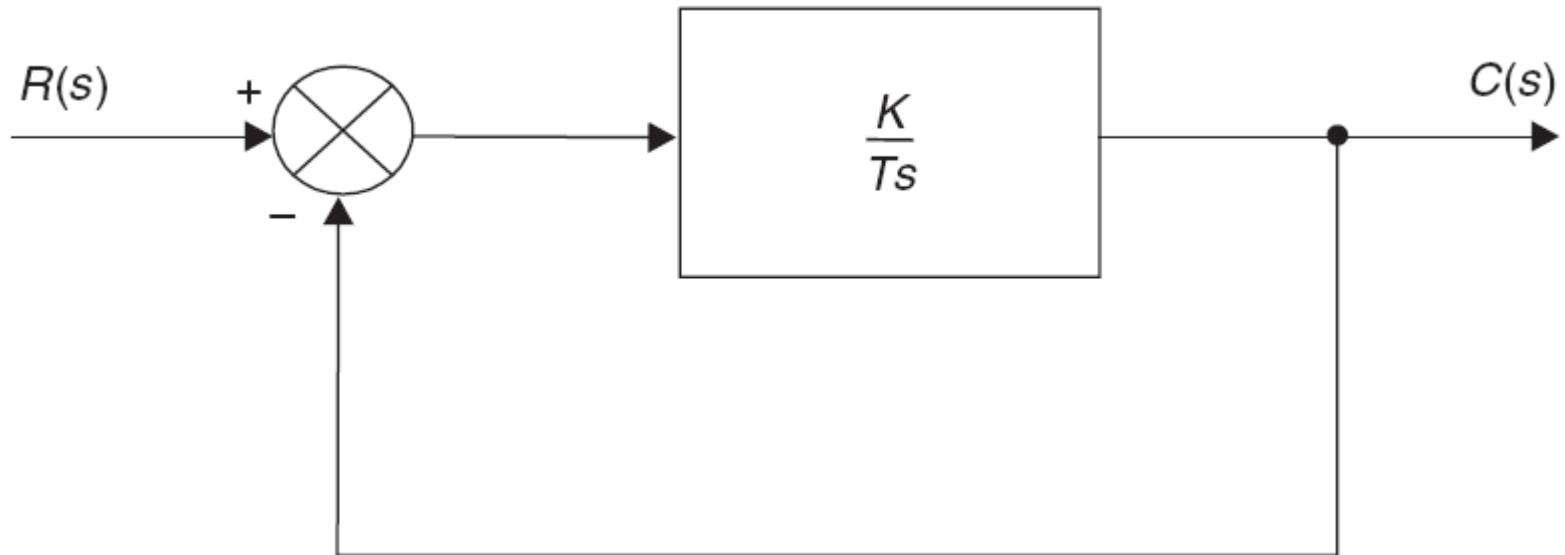


What is a Root Locus?

- Root Locus (of closed-loop poles)
 - Trajectory along which a (closed-loop) pole “moves” as a parameter, usually some open-loop gain K , of the system is varied.
 - Locus or curve describing the position of a closed-loop pole. This locus/curve is parameterised by the parameter K .
 - For each closed-loop pole there is a locus.

Introductory Example 1

- Block diagram



Introductory Example 1

- Open-loop

- Open-loop transfer function: $G(s)H(s) = \frac{K}{Ts}$

- Open-loop poles: $s = 0$

- Open-loop zeros: none

- Closed-loop poles (characteristic equation):

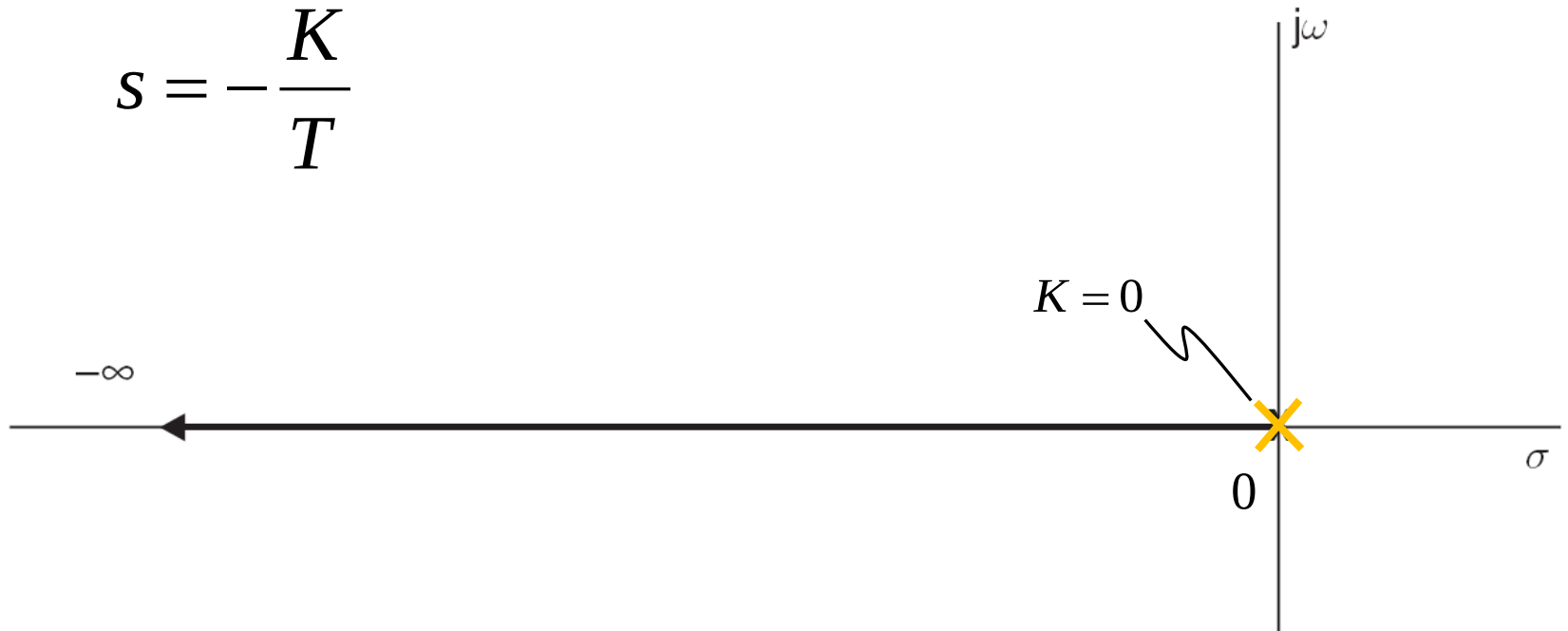
$$1 + G(s)H(s) = 0 \quad \Rightarrow \quad s = -\frac{K}{T}$$

- Conclusion: Closed-loop pole position depends on K

Introductory Example 1

- Root Locus (of the closed-loop pole)
 - A single open-loop pole implies a single locus.

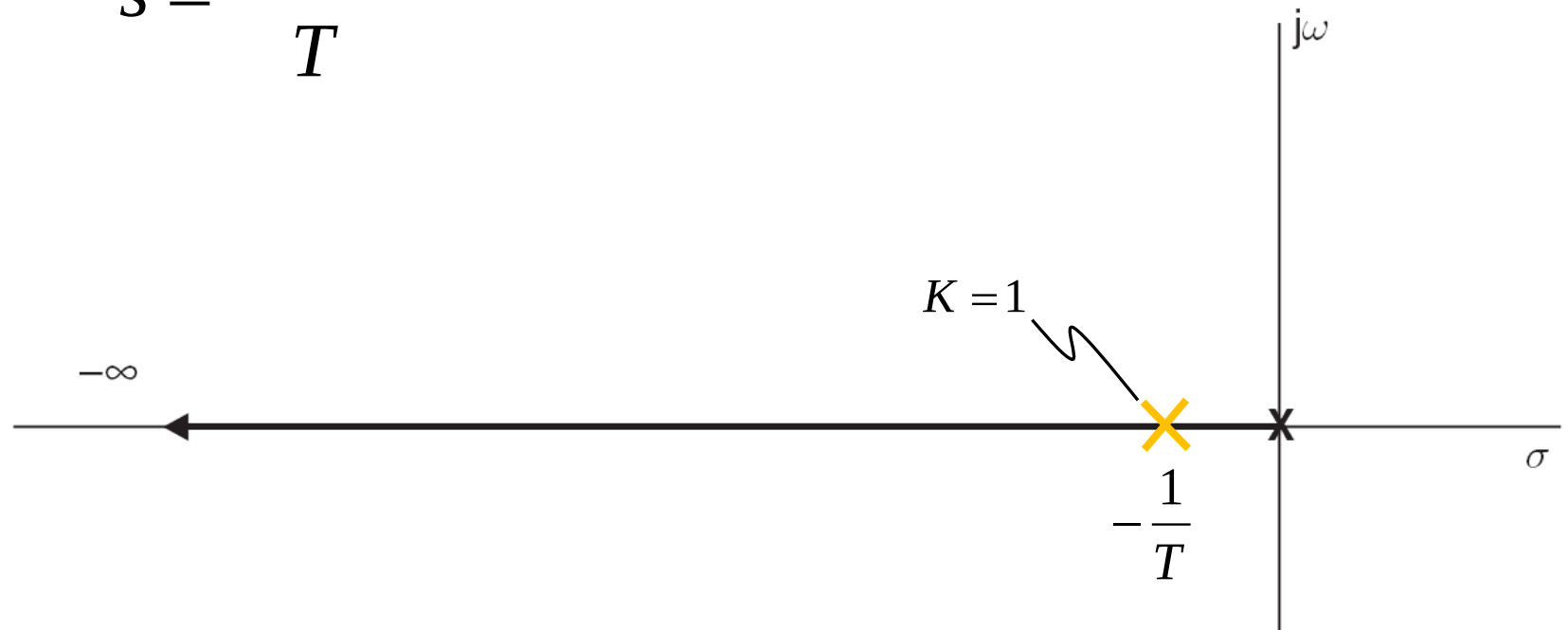
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Introductory Example 1

- Root Locus (of the closed-loop pole)

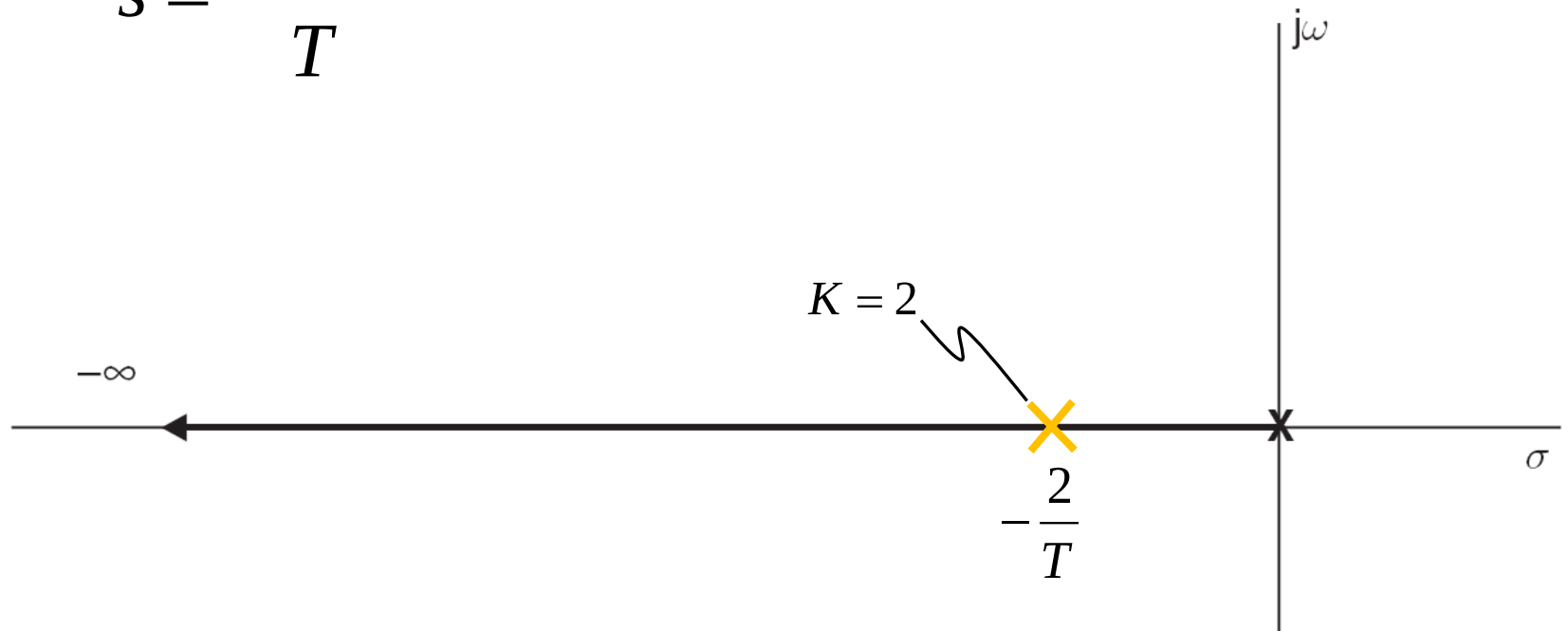
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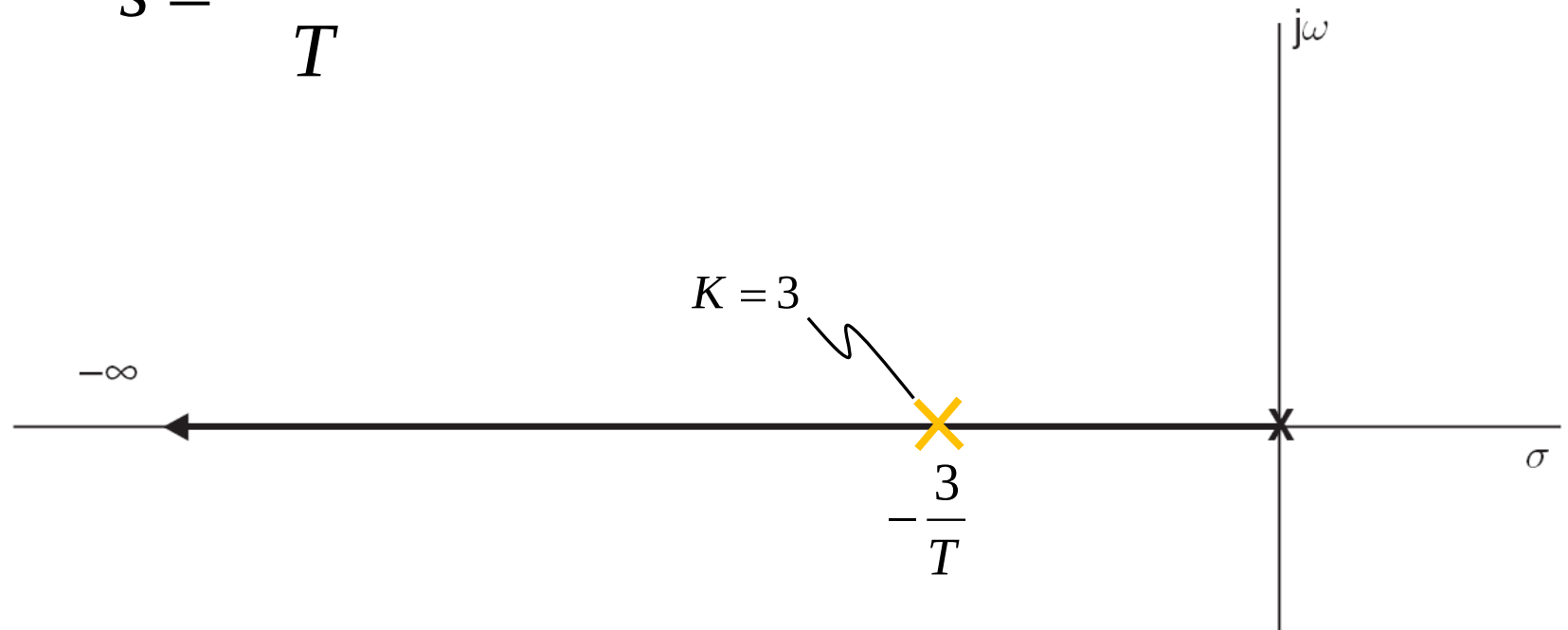
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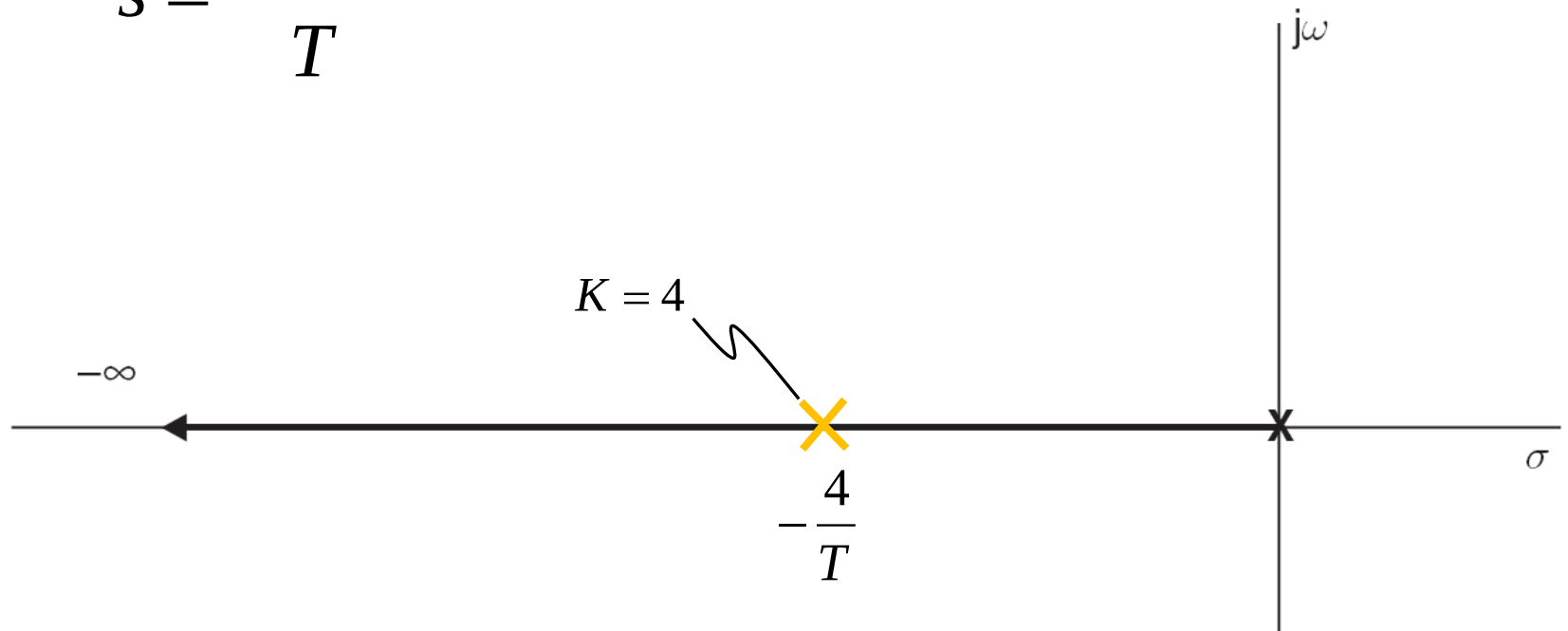
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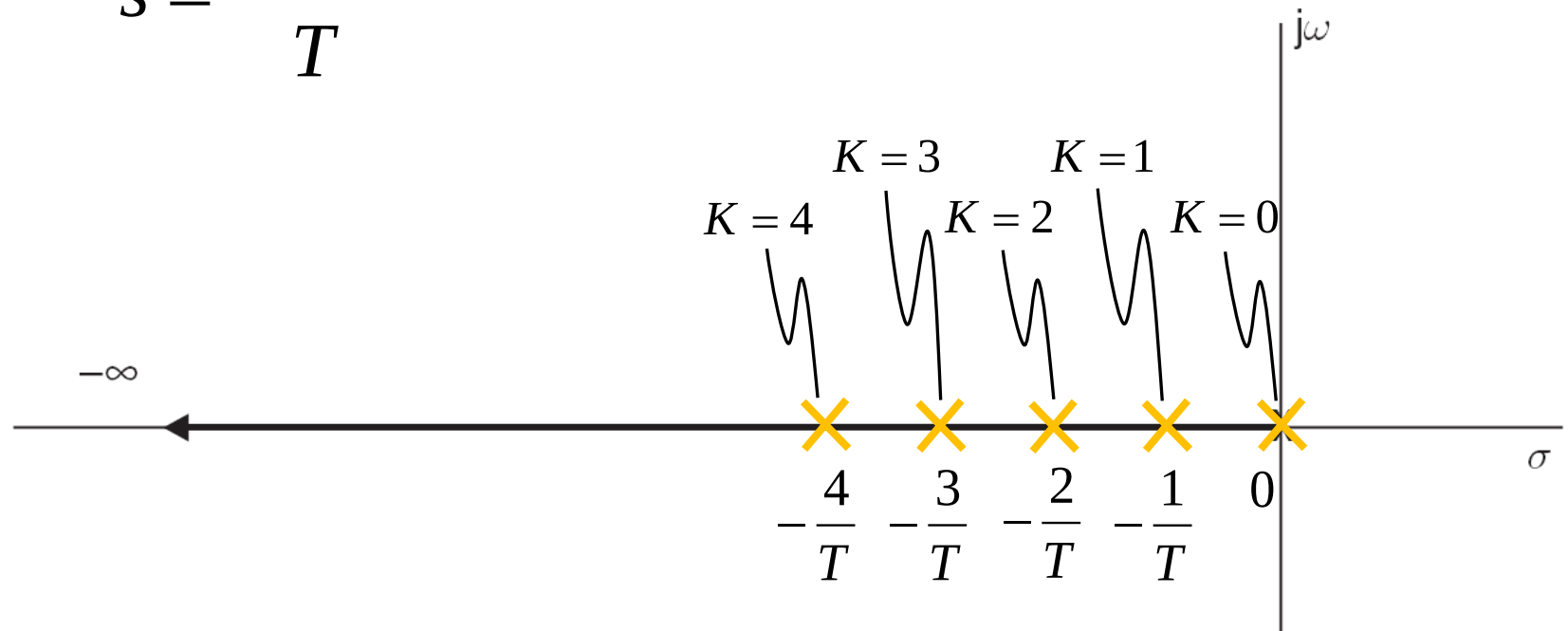
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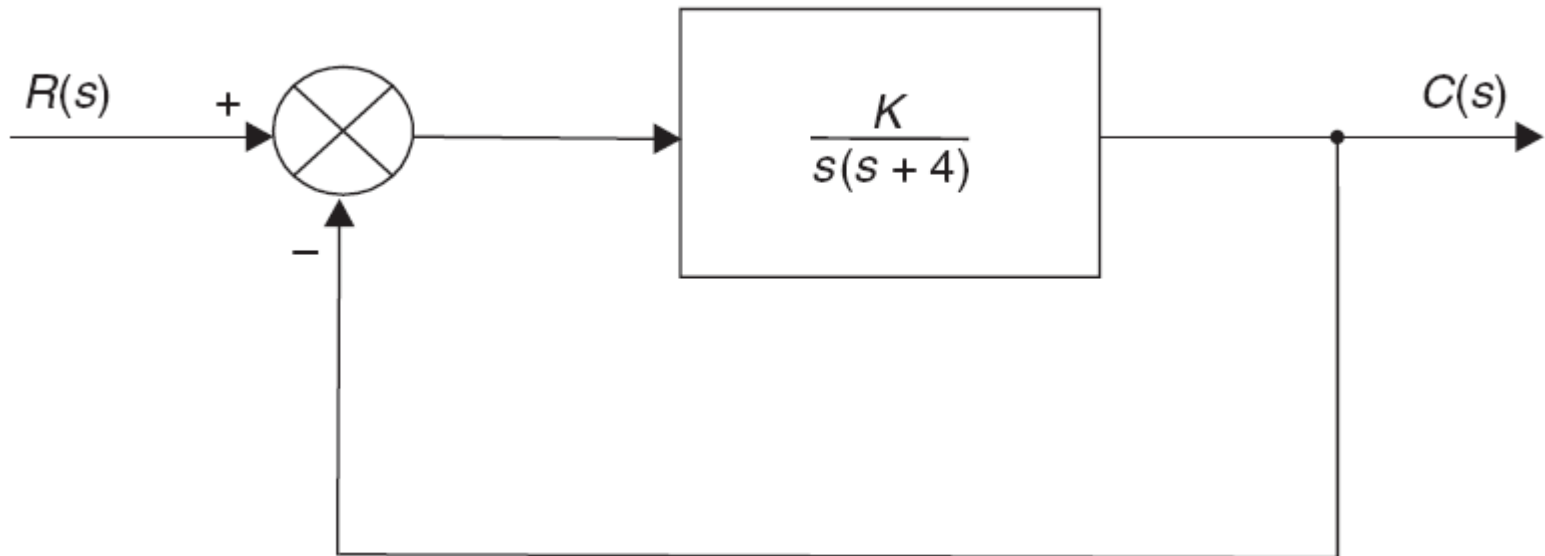
- Root Locus (of the closed-loop pole)

$$s = -\frac{K}{T}$$



Introductory Example 2

- Block diagram



Introductory Example 2

- Open-loop

- Open-loop transfer function: $G(s)H(s) = \frac{K}{s(s+4)}$
- Open-loop poles: $s = 0, -4$
- Open-loop zeros: none
- Characteristic equation:

$$1 + G(s)H(s) = 0 \quad \Rightarrow \quad s^2 + 4s + K = 0$$

- Conclusion: Poles' positions depend on K

Introductory Example 2

- Poles for different values of K

K	<i>Characteristic equation</i>	<i>Roots</i>
0	$s^2 + 4s = 0$	$s = 0, -4$
4	$s^2 + 4s + 4 = 0$	$s = -2 \pm j0$
8	$s^2 + 4s + 8 = 0$	$s = -2 \pm j2$
16	$s^2 + 4s + 16 = 0$	$s = -2 \pm j3.46$

$$s^2 + 4s + K = 0 \quad \Rightarrow \quad s = \frac{-4 \pm \sqrt{16 - 4K}}{2} = -2 \pm \sqrt{4 - K}$$

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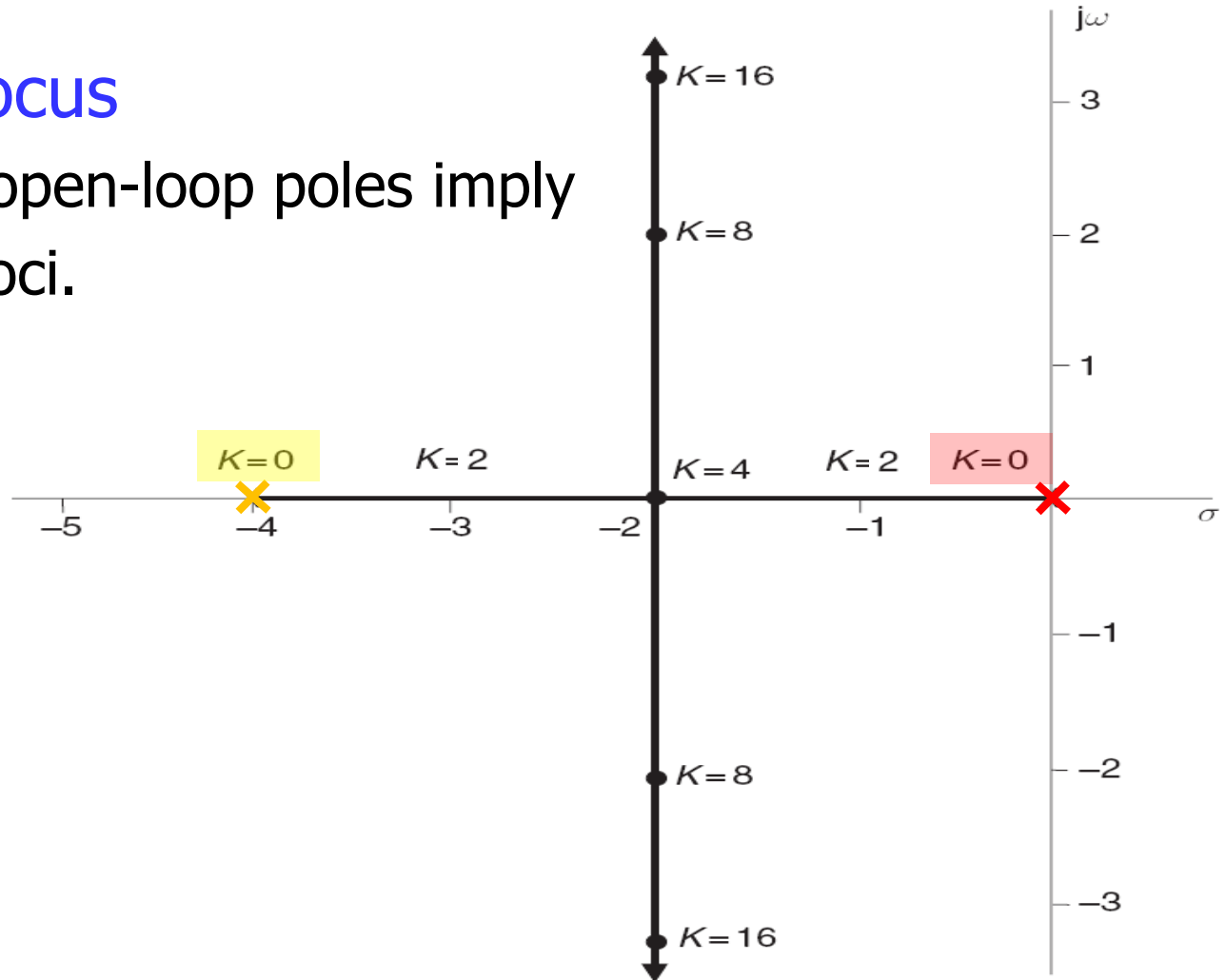
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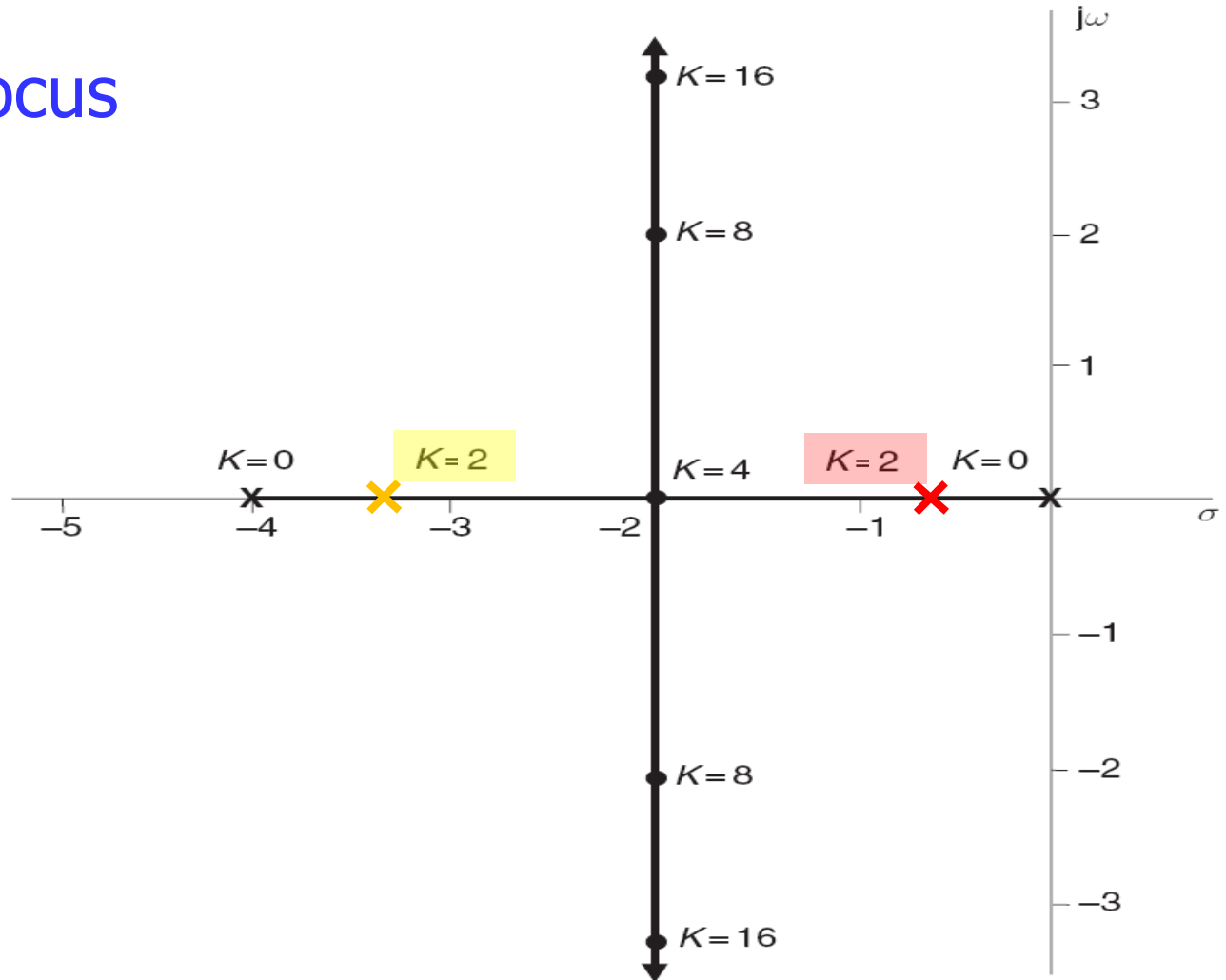
- Root Locus

- Two open-loop poles imply two loci.



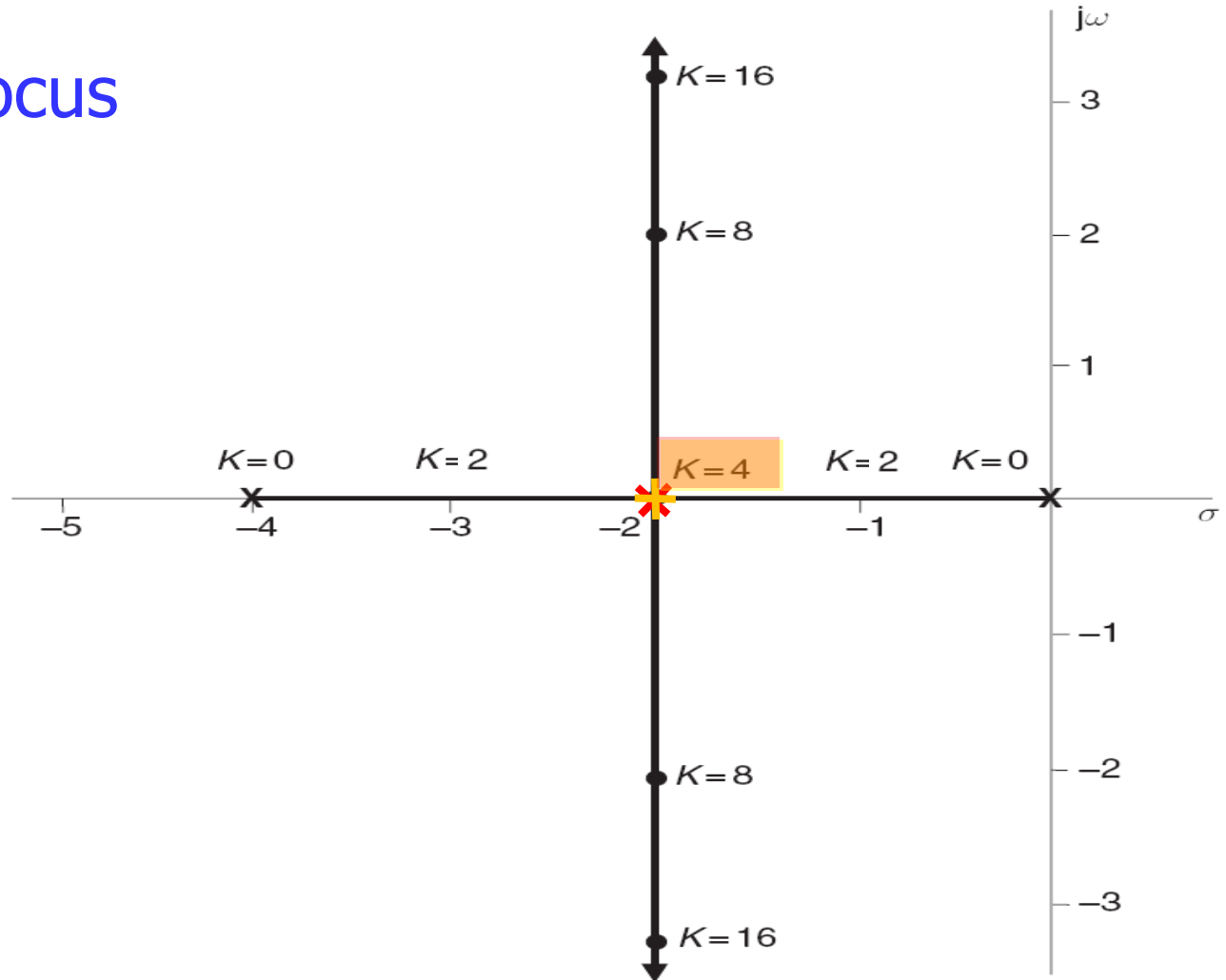
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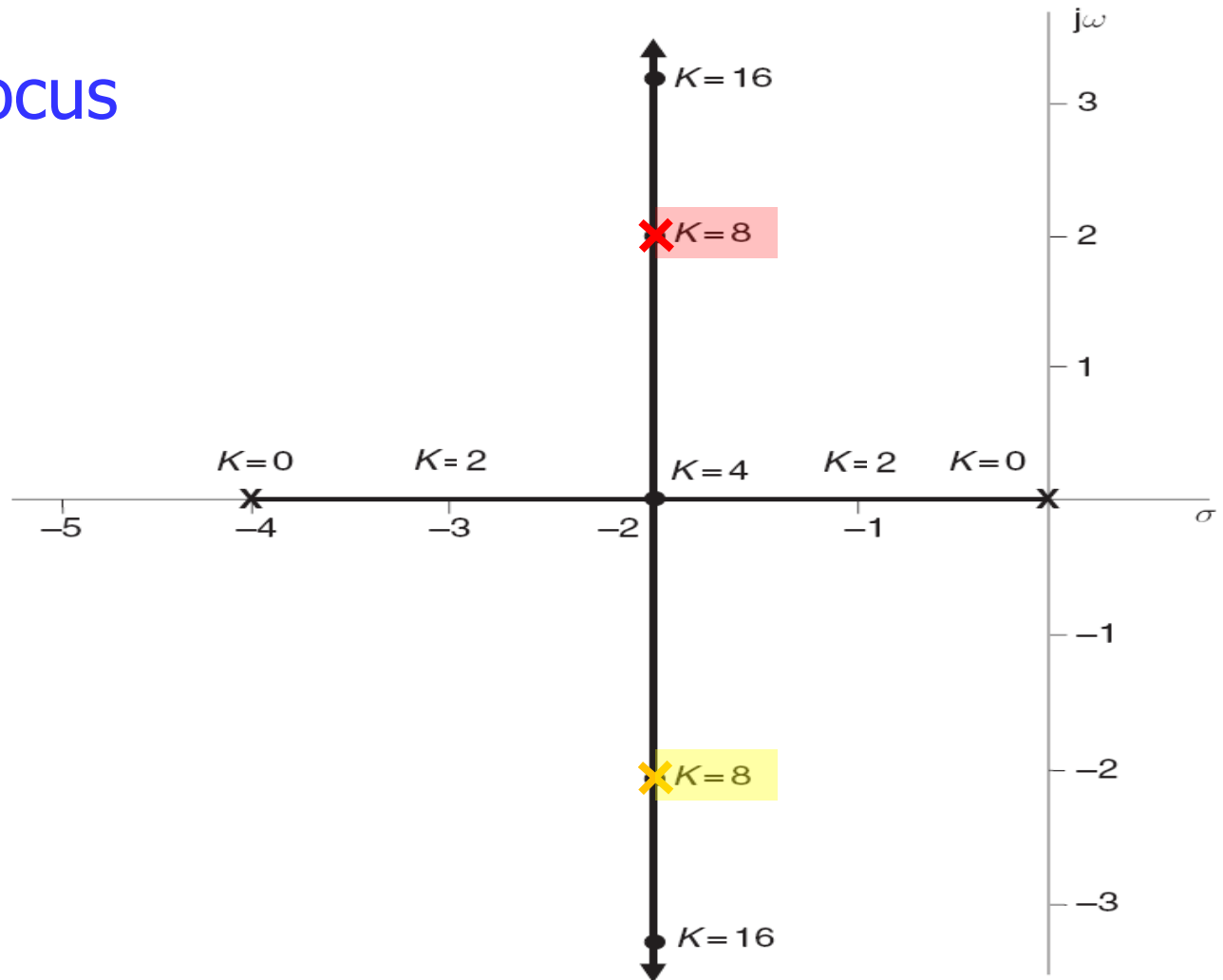
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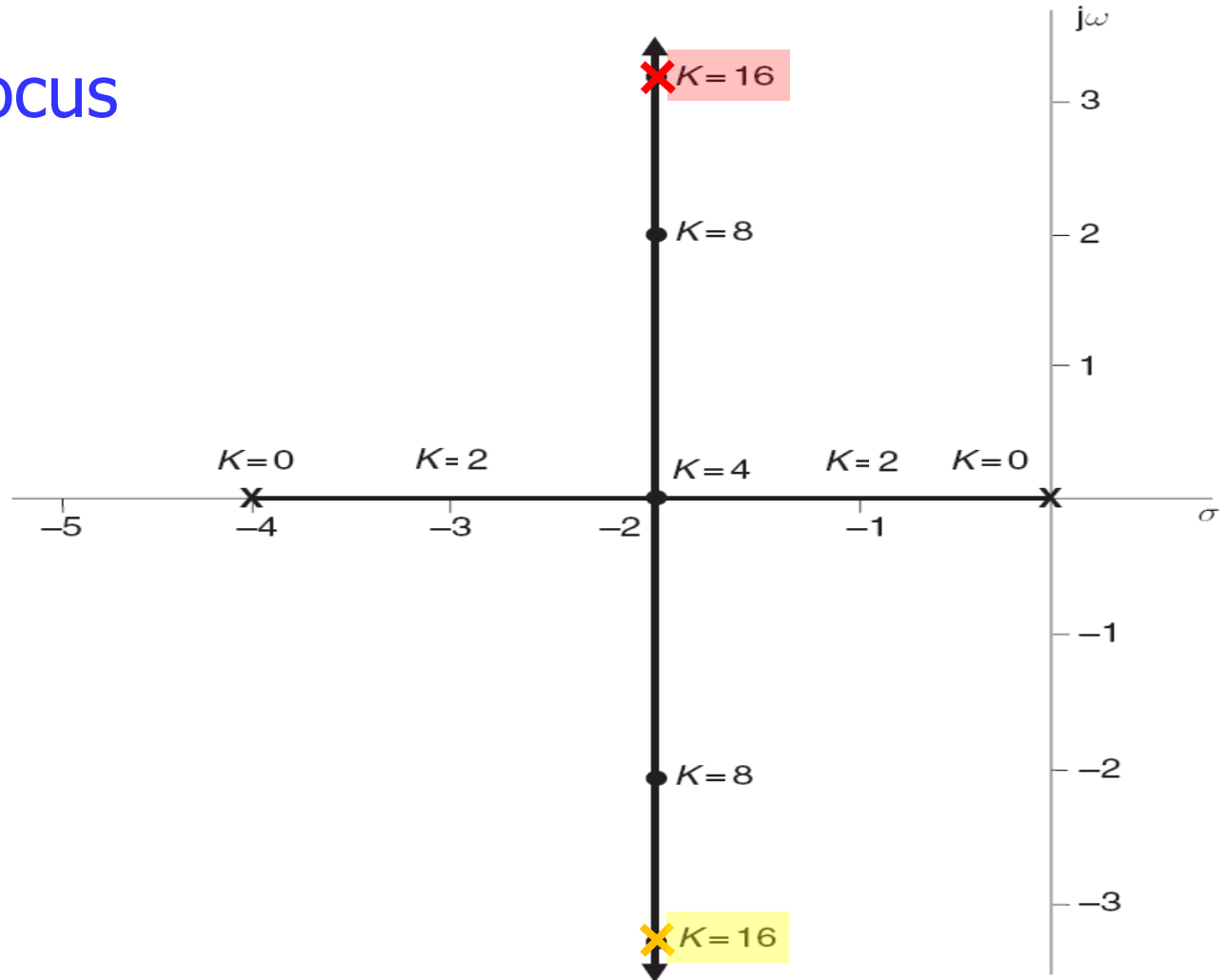
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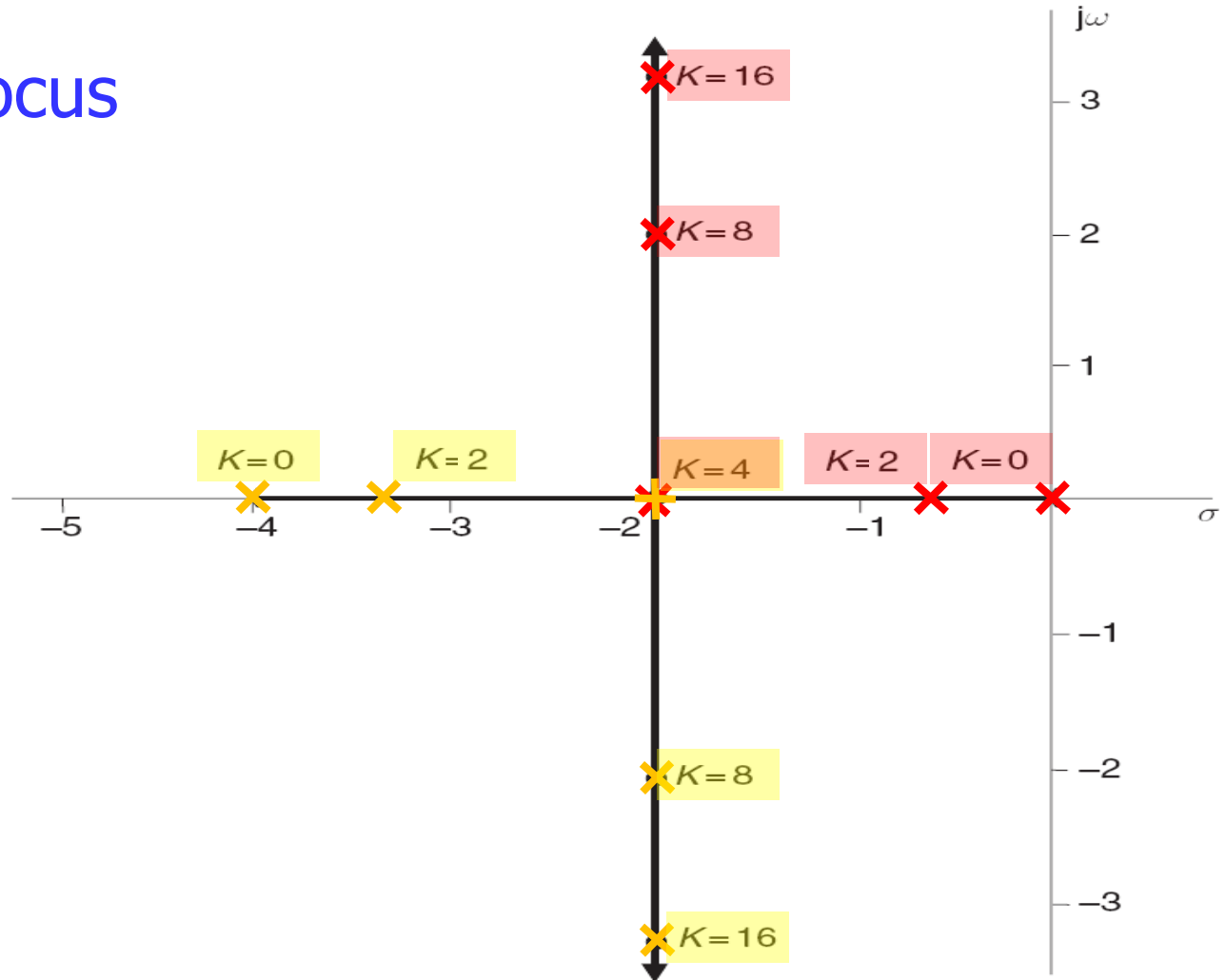
Introductory Example 2

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Introductory Example 2

- Root Locus



Root Locus

- Moral of the story ...
 - Changing the gain within a closed loop containing a (non-trivial) plant causes the closed-loop pole positions to deviate from the (open-loop) plant's pole positions.

Root Locus

- The Root Locus Problem

- Constructing the root locus for a given system means finding all ordered pairs $(\tilde{s}, \tilde{K})$ that satisfy the system's characteristic equation, that is,

$$1 + G(\tilde{s})H(\tilde{s})|_{K=\tilde{K}} = 0.$$

- The root locus rules (to come) ease this burden and enables us to swiftly sketch a root locus diagram with *minimal* effort.

Root Locus Rules

- Magnitude and Angle Criteria

$$1 + G(s)H(s) = 0 \Rightarrow G(s)H(s) = -1$$

- This implies that the magnitude and phase satisfy

$$|G(s)H(s)| = 1, \quad \angle(G(s)H(s)) = 180^\circ$$

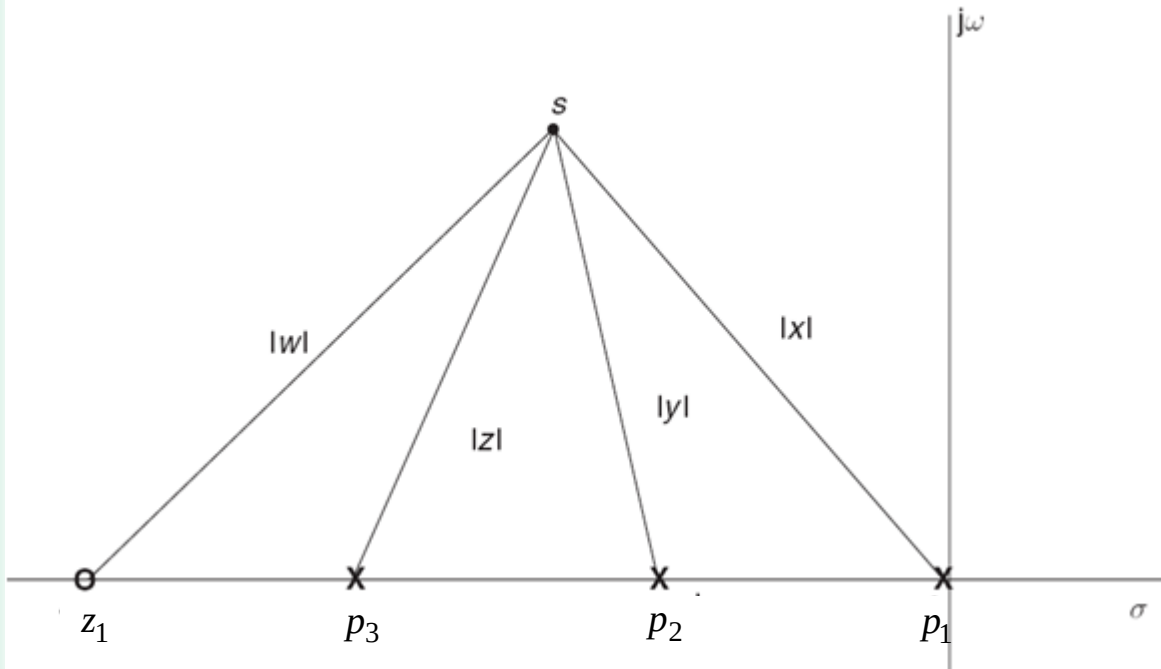
- Assumption:

$$G(s)H(s) = K \frac{N(s)}{D(s)}, \quad \begin{array}{l} \deg N(s) = m \\ \deg D(s) = n \end{array}$$

Root Locus Rules

- Magnitude Criterion

$$|G(s)H(s)| = 1 \Rightarrow |K| = \frac{|s - p_1| \times \cdots \times |s - p_n|}{|s - z_1| \times \cdots \times |s - z_m|}$$

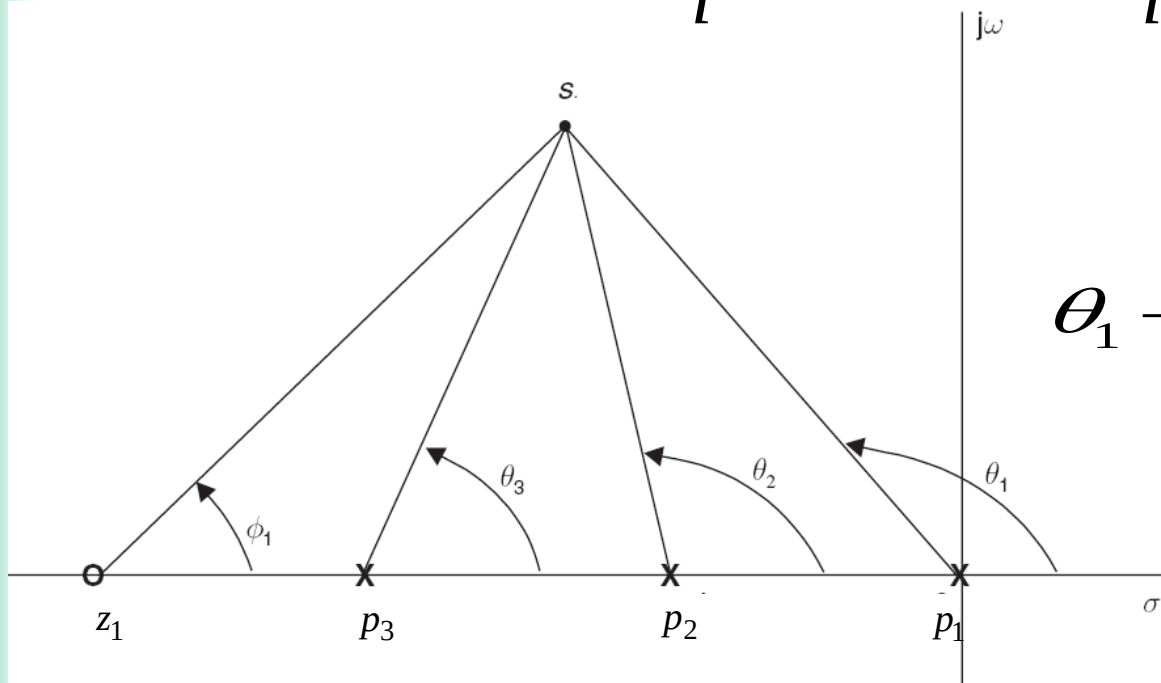


$$|K| = \frac{|x| \times |y| \times |z|}{|w|}$$

Root Locus Rules

- Angle Criterion

$$\angle \left(\frac{1}{G(s)H(s)} \right) = \sum_i \angle(s - p_i) - \sum_i \angle(s - z_i) = 180^\circ$$



$$\theta_1 + \theta_2 + \theta_3 - \phi_1 = 180$$

Root Locus Rules

- Starting points ($K = 0$)
 - Root loci start on open-loop poles
- Termination points ($K = \infty$)
 - Root loci terminate on open-loop zeros
- No. of distinct loci
 - Equal to the degree of the Characteristic Equation
- Symmetry of loci
 - Symmetric about the real axis

Root Locus Rules

- **Asymptotes** ($K \rightarrow \infty$)
 - For $K \gg 1$ loci approach straight-line asymptotes with angles

$$\alpha_k = \frac{180^\circ + k360^\circ}{n - m}, \quad k = 0, 1, \dots, (n - m - 1)$$

- **Asymptotes' real axis intercept**

- All of the above asymptotes meet the real axis at

$$\sigma_a = \frac{\sum_{i=1}^n p_i - \sum_{j=1}^m z_j}{n - m}$$

Note: *Imaginary parts* of poles & zeros do not contribute to σ_a .

Root Locus Rules

- Root locus segments on the real axis

- A point on the real axis is on a locus segment if there is an odd total number of poles & zeros to its right.

- Breakaway/break-in points

- At points where loci break away from or into the real axis

$$\left. \frac{dK(s)}{ds} \right|_{s=\sigma_b} = 0 \quad \text{with} \quad K(s) = -\frac{D(s)}{N(s)}$$

- Angles of departure & arrival

- Follow from the angle criterion in a small neighbourhood of the point (i.e. pole or zero) of interest.

Tutorial Exercises & Homework

- Tutorial Exercises

- Burns, Examples 5.14 and 5.15
- D'Azzo & Houpis, Section 7-10, Example 2, pp. 235 – 240.

- Homework

- Burns, Sections 5.3.1 and 5.3.3

Conclusion

- Root Locus Introductory Examples
- Root Locus Construction rules
- Burns, Sec 5.3.1, 5.3.3 (**Self-study!**)
 - Sec 5.3.3 suggests contours of constant ζ that can be extended to contours of constant ω_n , ω_d and $\zeta\omega_n$. (**As discussed earlier this semester.**)
- Tutorial Exercises & Homework

Next Attraction! – Miss It & You'll Miss Out!

- Applications of the Root Locus Technique
(Burns, Chapter 5)

...



Thank you!
Any Questions?